

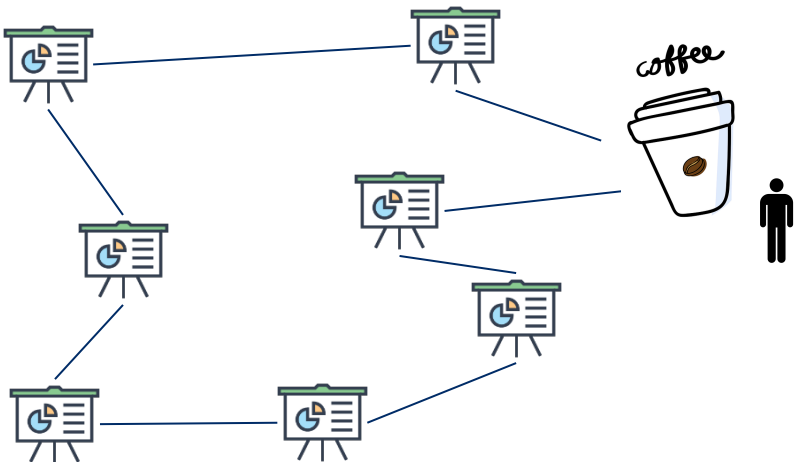


Attention, Learn to Solve Routing Problems!

Wouter Kool, Herke van Hoof, Max Welling



UNIVERSITY OF AMSTERDAM



Travelling Scientist Problem (TSP)

International Conference on Learning Representations 2019

Published as a conference paper at ICLR 2019

ATTENTION, LEARN TO SOLVE ROUTING PROBLEMS!

Wouter Kool
University of Amsterdam
w.w.m.kool@uva.nl

Herke van Hoof
University of Amsterdam
h.c.vanhoof@uva.nl

Max Welling
University of Amsterdam
m.welling@uva.nl

TSP* is (NP-)hard!

* Travelling Salesman Problem (TSP)

What does it mean?

Finding *optimal* solutions for *all* problem instances

MISSION:
IMPOSSIBLE

* unless $P = NP$

Finding *acceptable* solutions for *relevant* problem instances

MISSION:
~~IMPOSSIBLE~~

We use HEURISTICS

Can be seen as 'rules of thumb'

'next location should be nearby'

Crafting of heuristics is similar to feature engineering

**HARD
WORK**

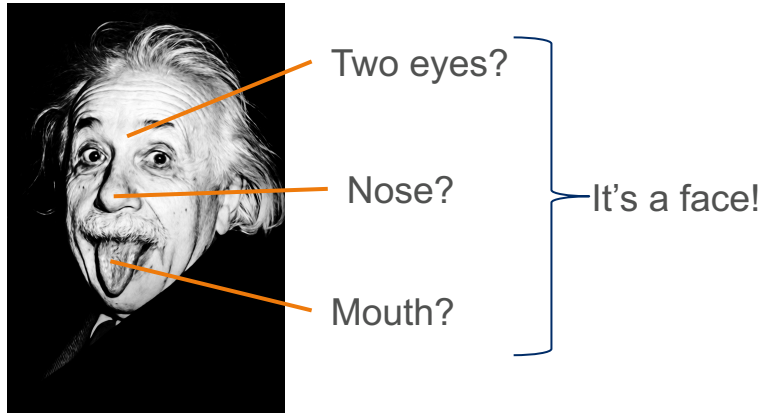
Computer Vision Features
(SIFT, etc.)

Feature engineering

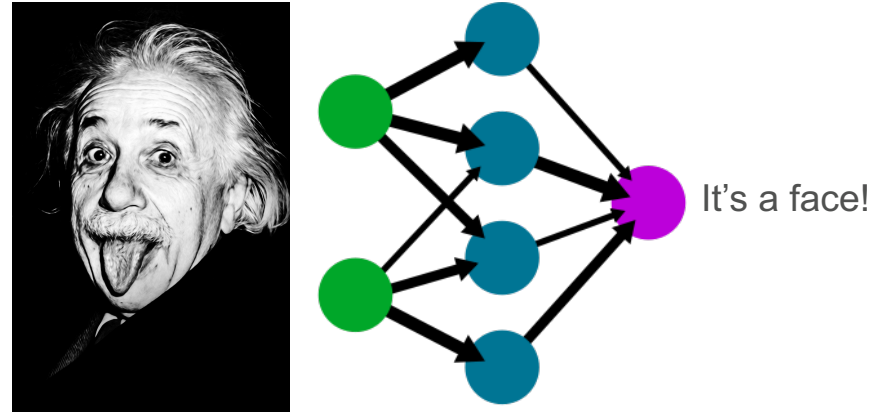
- Needs expert knowledge
- Time consuming hand-tuning

So what do we do?

Crafting of heuristics is similar to feature engineering

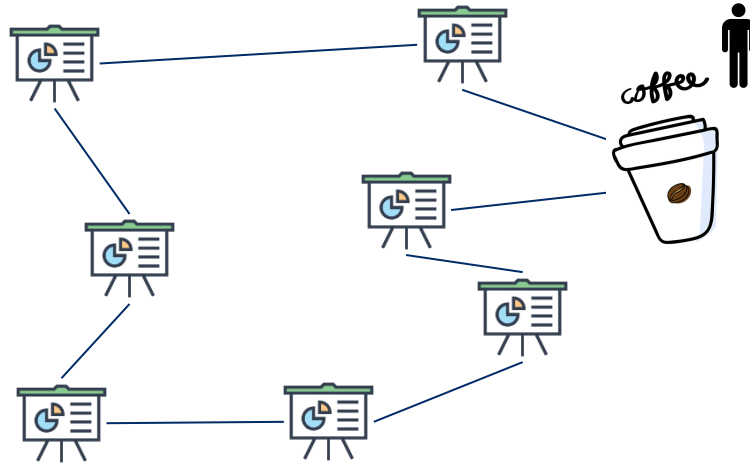


Traditional approach
Feature engineering



Deep Learning
No feature engineering

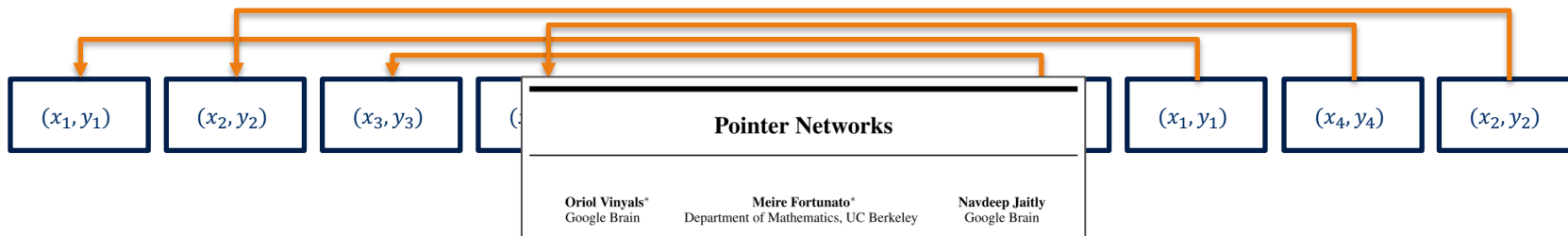
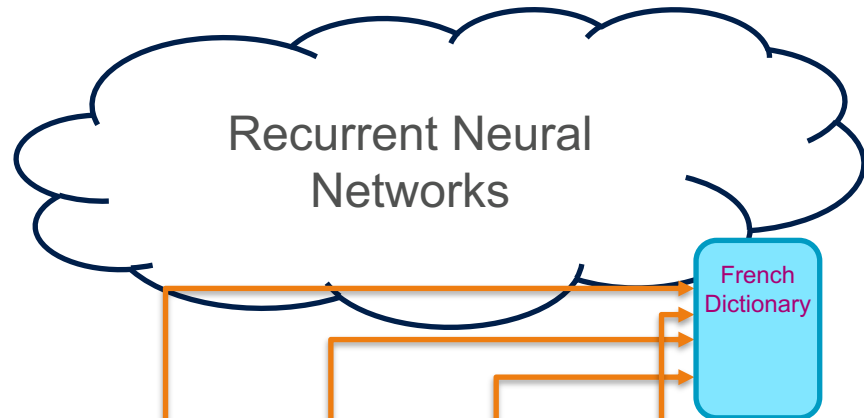
Back to our problem



'Translate' problem into solution



Idea

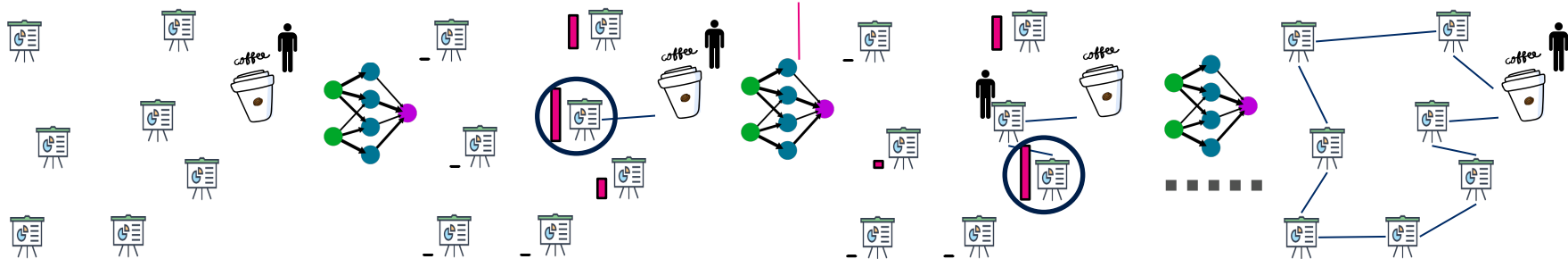


How does that work?

Instance $s = ((x_1, y_1), (x_2, y_2), \dots, (x_n, y_n))$

Model $p_\theta(\pi_t | s, \pi_{<t}) = p_\theta(\text{next node} | \text{partial tour})$

Solution $\pi = (\pi_1, \pi_2, \dots)$ with length $L(\pi)$



Sample $\pi_1 \sim p_\theta(\pi_1 | s)$

Sample $\pi_2 \sim p_\theta(\pi_2 | s, \pi_1)$

Sample $\pi_t \sim p_\theta(\pi_t | s, \pi_{<t})$

Randomized algorithm with expected cost:

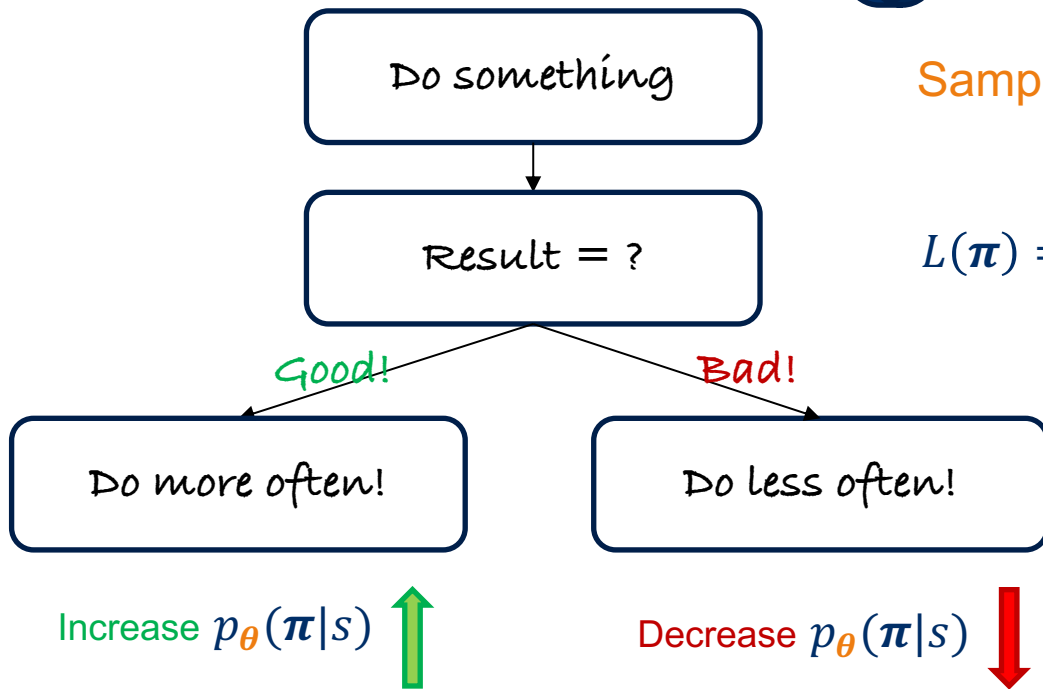
$$E_{p_\theta(\pi | s)} [L(\pi)]$$

How to optimize θ ?

NEURAL COMBINATORIAL OPTIMIZATION WITH REINFORCEMENT LEARNING

Irwan Bello*, Hieu Pham*, Quoc V. Le, Mohammad Norouzi, Samy Bengio
 Google Brain
 {ibello, hyhieu, qvl, mnorouzi, bengio}@google.com

REINFORCE (for dummies)



Sample $\pi \sim p_{\theta}(\cdot | s)$

$L(\pi) = 7.43$

We need a *baseline* to compare against: *rollout earlier model*

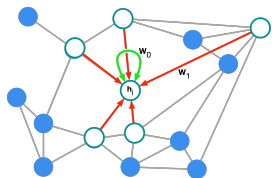
$\pi^{bl} \sim p_{\theta^{bl}}(\cdot | s)$ (greedy!)

$L(\pi^{bl}) = 6.89$

What's the model architecture?

$$p_{\theta}(\pi_t | s, \pi_{<t})$$

Graph convolutions



Attention Is All You Need

Ashish Vaswani*
 Google Brain
 avaswani@google.com

Noam Shazeer*
 Google Brain
 noam@google.com

Niki Parmar*
 Google Research
 nikip@google.com

Jakob Uszkoreit*
 Google Research
 usz@google.com

Llion Jones*
 Google Research
 llion@google.com

Aidan N. Gomez†
 University of Toronto
 aidan@cs.toronto.edu

Lukas Kaiser*
 Google Brain
 lukaszkaizer@google.com

Illa Polosukhin*†
 illia.polosukhin@gmail.com

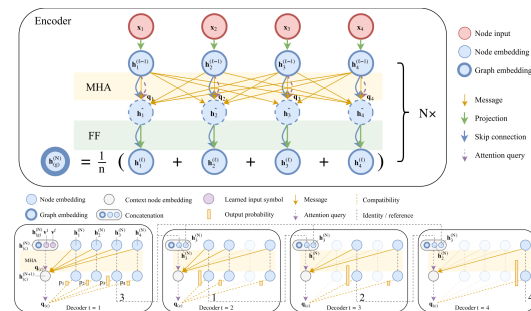
Read the paper...

ATTENTION, LEARN TO SOLVE ROUTING PROBLEMS!

Wouter Kool
 University of Amsterdam
 w.w.m.kool@uva.nl

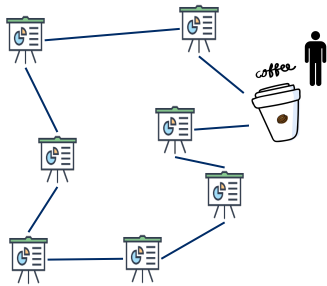
Herke van Hoof
 University of Amsterdam
 h.c.vanhoof@uva.nl

Max Welling
 University of Amsterdam
 m.welling@uva.nl



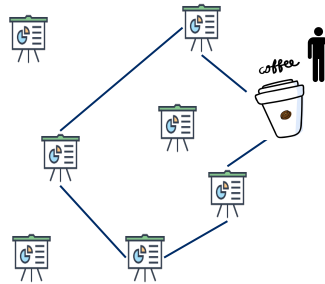
Experiments

Travelling Salesman Problem (TSP)



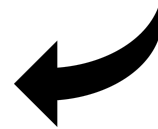
Minimize length
Visit all nodes

Orienteering Problem (OP)



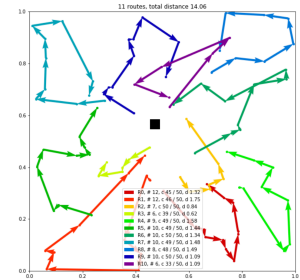
Maximize total prize
Max length constraint

(Stochastic) Prize Collecting TSP ((s)PCTSP)



Minimize length +
penalties of unvisited nodes
Collect minimum total prize

Vehicle Routing Problem (VRP)



Minimize length
Visit all nodes
Total route demand must
fit vehicle capacity

Train for each problem, *same hyperparameters!*

Results Attention Model + Rollout Baseline

- Improves over classical heuristics!
- Improves over prior learned heuristics!
 - Attention Model improves
 - Rollout helps significantly
- Gets close to single-purpose SOTA (20 to 100 nodes!)
 - TSP 0.34% to 4.53% (greedy)
 - TSP 0.08% to 2.26% (best of 1280 samples)

The end!

- Learning algorithms for optimization problems is promising
- Especially for less well-studied problems
- Can deal with uncertainty, specialize to data distribution, etc.

Thank you for your attention!