

Linear Relaxations for the Maximum Stable Set Problem: a computational study

M. Giandomenico¹, A. N. Letchford², F. Rossi and S. Smriglio¹

¹ Dipartimento di Informatica, Università di L'Aquila, Italy
{giandomenico, rossi, smriglio}@di.univaq.it
² Department of Management Science, Lancaster University, UK
A.N.Letchford@lancaster.ac.uk

The *Maximum Stable Set Problem* on a graph $G = (V, E)$ is a well-known combinatorial optimization problem, with a huge number of applications. Although the *Stable Set Polytope* has been extensively researched, the many relevant theoretical results on its structure have not led to significant computational success. In fact, it appears a hard task to strengthen the basic LP relaxation consisting of clique and non-negativity inequalities (see [1], [7] and [8]). On the other hand, Semidefinite Programming (SDP) techniques appear to be much more promising since they provide stronger relaxations (see, for instance, [2], [3] and [4]). Unfortunately, these may be affected by numerical instabilities and the lack of fast re-optimization algorithms prevents their embedding in a branch-and-bound scheme.

In this talk we present an extended linear relaxation obtained by the application of the Lovász-Schrijver $M(K, K)$ operator [6]. Roughly speaking, the $M(K, K)$ operator “squares” the size of a linear system by multiplying pairs of constraints together. Applying the $M(K, K)$ operator to an LP relaxation consisting of clique and non-negativity inequalities yields the extended linear relaxation investigated in [5]. After a review of the theoretical properties of such formulation, we present a computational experience comparing strength and limitations of the LP and SDP approaches.

References

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